Effect of dissipation factor on reflected and transmitted powers of a structure containing left-handed material waveguide

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ABSTRACT

In this paper a waveguide structure consisting of a pair of left-handed material (LHM) and dielectric slabs inserted in vacuum is investigated theoretically. Two cases of the LHM are considered, loss-less case and loss case as well as the frequency dependence of permittivity and permeability of it is taken into account. Maxwell's equations are used to determine the electric and magnetic fields of the incident waves at each layer. Snell's law is applied and the boundary conditions are imposed at each layer interface to calculate the reflected, transmitted and loss powers of the structure. Numerical results are illustrated to show the effect of frequency, angle of incidence and LHM thickness on the mentioned powers when the dissipation factor changes. The obtained results are in agreement with the law of conservation of energy.

Keywords: Electromagnetic waves; left-handed material; dissipation factor; frequency; Reflected power; transmitted power

1. INTRODUCTION

Metamaterials (sometimes termed left-handed materials (LHMs)) are materials whose permittivity  and permeability  are both negative and consequently have negative index of refraction. These materials are artificial and theoretically discussed first by Veselago [1] over 40 years ago. The first realization of such materials, consisting of split-ring resonators (SRRs) and continuous wires, was first introduced by Pendry [2,3].

Regular materials are materials whose  and  are both positive and termed right handed materials (RHMs). R. A. Shelby et al [4] have studied negative refraction in LHMs. I. V. Shadrivov [5] has investigated nonlinear guided waves in LHMs. N. Garcia et al [6] have shown that LHMs don't make a perfect lens.

Kong [7] has provided a general formulation for the electromagnetic wave interaction with stratified metamaterial structures. M. F. Ubeid et al [8] have discussed the propagation of electromagnetic waves through a dielectric counterpart of left-handed material.
2. THEORY

We consider four regions each with permittivity $\varepsilon_\ell$ and permeability $\mu_\ell$, where $\ell$ represents the region order. Region 1 and 4 are vacuums ($\varepsilon_o$, $\mu_o$), Region 2 is a regular dielectric ($\varepsilon_2$, $\mu_2$), Region 3 is a metamaterial ($\varepsilon_3(\omega)$, $\mu_3(\omega)$).

A polarized plane wave in Region 1 incident on the plane $z=0$ at some angle $\theta$ relative to the normal to the boundary (see Fig. 1).
The electric field in each region is [7, 11]:

$$\vec{E}_\ell = (A_\ell e^{ik_iz} + B_\ell e^{-ik_iz}) e^{i(k_{\ell x} x - \omega t)} \hat{y}$$

(1)

We use Maxwell's equation as done by [16] to find corresponding magnetic field $\vec{H}_\ell$:

$$\vec{H}_\ell = \frac{1}{\mu_\ell \omega} \left[ (A_\ell k_{\ell z} e^{ik_iz} + B_\ell k_{\ell z} e^{-ik_iz}) \hat{z} + (-A_\ell k_{\ell z} e^{ik_iz} + B_\ell k_{\ell z} e^{-ik_iz}) \hat{x} \right] e^{i(k_{\ell x} x - \omega t)}$$

(2)

Where $A_\ell$ and $B_\ell$ are the amplitudes of forward and backward traveling waves. $k_\ell = \omega / c$ is the wave vector inside the material and $n_\ell$ is the refractive index of it. Matching the boundary conditions for $\vec{E}$ and $\vec{H}$ fields at each layer interface, that is at $z = 0$, $E_1 = E_2$ and $H_1 = H_2$ and so on. This yields six equations with six unknown parameters [11, 13, 16]:

$$A_1 + B_1 = A_2 + B_2$$

(3)
\[ \frac{k_{1z}}{\mu_1} (A_1 - B_1) = \frac{k_{2z}}{\mu_2} (A_2 - B_2) \]  

(4) 

\[ A_2 e^{ik_{2z}d_2} + B_2 e^{-ik_{2z}d_2} = A_3 e^{ik_{3z}d_2} + B_3 e^{-ik_{3z}d_2} \]  

(5) 

\[ \frac{k_{2z}}{\mu_2} (A_2 e^{ik_{2z}d_2} - B_2 e^{-ik_{2z}d_2}) = \frac{k_{3z}}{\mu_3} (A_3 e^{ik_{3z}d_2} - B_3 e^{-ik_{3z}d_2}) \]  

(6) 

\[ A_3 e^{ik_{3z}(d_2 + d_3)} + B_3 e^{-ik_{3z}(d_2 + d_3)} = A_4 e^{ik_{4z}(d_2 + d_3)} \]  

(7) 

\[ \frac{k_{3z}}{\mu_3} (A_3 e^{ik_{3z}(d_2 + d_3)} - B_3 e^{-ik_{3z}(d_2 + d_3)}) = \frac{k_{4z}}{\mu_4} A_4 e^{ik_{4z}(d_2 + d_3)} \]  

(8) 

Where \( k_{1z} = k_{2z} = k_{3z} = k_{4z} \equiv \text{Snell's law.} \) 

Letting \( A_1 = 1 \) and solving the obtained equations for the unknown parameters enables us to calculate the reflection and transmission coefficients \( B_1 \) and \( A_4 \) [11, 16]. The reflected power \( R \) and the transmitted power \( T \) are given by [11, 16]: 

\[ R = B_1 B_1^* \quad T = \left( \frac{k_{4z}}{k_{1z}} \right) A_4 A_4^* \]  

(9) 

Where \( B_1^* \) and \( A_4^* \) are the complex conjugate of \( B_1 \) and \( A_4 \) respectively. 

The law of conservation of energy is given by [11, 14, 15]: 

\[ R + T = 1 - P_{\text{loss}} \]  

(10) 

Where, \( P_{\text{loss}} \) is the loss power due to losses in LHM and \( k_{1z} \) is given by: 

\[ k_{1z} = \frac{\omega}{c} \sqrt{n_\varepsilon^2 - n_1^2 \sin^2 \theta_1} \]  

(11) 

3. NUMERICAL RESULTS 

For the LHM in region 3 we employ a dispersive one with \( \varepsilon_3 \) and \( \mu_3 \) appeared in [2, 3, 16]: 

\[ \varepsilon_3 (\omega) = 1 - \frac{F_e \omega_{ep}^2}{\omega^2 - \omega_{eo}^2 + i\gamma_e \omega} \]  

(12)
where \( \omega_{ep} \) and \( \omega_{mp} \) are the electric and magnetic plasma frequencies, \( \omega_{eo} \) and \( \omega_{mo} \) are the electric and magnetic resonance frequencies. \( F_e \) and \( F_m \) are the scaling filling parameters. \( \gamma_e \) and \( \gamma_m \) are the electric and magnetic dissipation factors.

We have used the following parameters appearing in [16]: \( \omega_{mp} = 2\pi \times 10.95 \text{ GHz} \), \( \omega_{mo} = 2\pi \times 10.1 \text{ GHz} \), \( F_m = .26 \), \( \omega_{ep} = 2\pi \times 13.3 \text{ GHz} \), \( \omega_{eo} = 2\pi \times 10.3 \text{ GHz} \), \( F_e = .37 \).

Two cases of the LHM are considered, loss-less case \( (\gamma_e = \gamma_m = \gamma = 0) \) and loss case \( (\gamma_e = \gamma_m = \gamma \neq 0) \). In the loss-less case, the frequency range in which \( \varepsilon_3(\omega) \) and \( \mu_3(\omega) \) are negative extends from 10.3 up to 11.5 GHz.

The operating frequency is assumed to be \( 2\pi \times 11 \text{ GHz} \). This frequency is chosen by an arbitrary decision, but it must be in the frequency band where the permittivity and permeability of the LHM are both simultaneously negative.

Region 1, 2 and 4 in Fig. 1 are assumed to be loss-less. The thickness of each of LHM and dielectric slabs is equal to one half-wavelength long at the operating frequency. T and R are calculated numerically as stated above.

In Fig. 2 we show a calculation of reflected, transmitted and loss powers of the considered structure as a function of frequency for three values of dissipation factor of the LHM \( (\gamma = 0, .1 \text{ and } .2 \text{ GHz}) \) and for 30\(^\circ\) angle of incidence.

The frequency is changed between 9 GHz and 12 GHz, because the simultaneously negative permittivity and permeability can be realized in this range in all cases, according to Eq (12) and (13). As confirmed from Fig. 2, the powers show increasing, decreasing and oscillatory behaviors in different frequency ranges.

The interpretation of this is as follows: the transmission is null above 11.5 GHz frequency, where all incident radiation is being reflected. In this band \( \varepsilon_3(\omega) \) and \( \mu_3(\omega) \) are different in signs, and then \( n_3 \) is imaginary, this is because

\[
 n_3 = \sqrt{\frac{\varepsilon_3 \mu_3}{\varepsilon_0 \mu_0}}
\]

In 10.3-11.5 GHz band the transmission is very good. In this band \( \varepsilon_3(\omega) \) and \( \mu_3(\omega) \) are both negative, and then \( n_3 \) is real. At 10.1 and 10.2 GHz frequencies the transmitted power is zero because \( \mu_3(\omega) \) is positive and \( \varepsilon_3(\omega) \) is negative and then \( n_3 \) is imaginary.

In 9-10 GHz band the transmitted power is not zero because both \( \varepsilon_3(\omega) \) and \( \mu_3(\omega) \) are positive and then \( n_3 \) is real.

This means that electromagnetic waves will only propagate in a medium that has a real index of refraction [16]. This interpretation is presented for loss-less case and can be applied on the loss case of LHM.
Fig. 2. Reflected, transmitted and loss powers as a function of frequency.
Figure 3 illustrates the variation of reflected, transmitted and loss powers with the angle of incidence. The angle of incidence is changed between 0° and 90° to realize all possible angles of incidence.

Clearly the reflected power increases while the transmitted and loss powers decrease with the angle of incidence. At 90° the reflected power is maximum while the transmitted and loss powers are minimum at that angle for any value of dissipation factor.

The role of the dissipation factor is clear at angles below 90°. The reflected and transmitted powers decrease while the loss power increases with the dissipation factor for any angle below 90°.

Figure 4 demonstrates the effect of thickness of LHM on the reflected, transmitted and loss powers respectively at 30° angle of incidence.

The slab thickness is changed from zero to 30 mm. It is noticed from the figure that the reflected power changes periodically for all dissipation factors.

The transmitted power shows the same property for γ = 0 GHz, it shows oscillatory decreasing when γ = 1 and 2 GHz.

On the other hand the loss power shows oscillatory increasing behavior with the increasing values of the dissipation factor.
Fig. 3. Reflected, transmitted and loss powers against the angle of incidence.
Fig. 3 (continue). Reflected, transmitted and loss powers against the angle of incidence.

Fig. 4. Reflected, transmitted and loss powers versus thickness of LHM.
Fig. 4 (continue). Reflected, transmitted and loss powers versus thickness of LHM.
4. CONCLUSION

The transmission and reflection of electromagnetic waves by a multilayered structure consisting of a pair of LHM and dielectric slabs situated in free space have been studied with effect of the dissipation factor. The followed method is based on Maxwell's equations and matching the boundary conditions for the electric and magnetic fields at each layer interface.

The frequency dependence of $\varepsilon$ and $\mu$ of the LHM is taken into account. The dependence of the reflected, transmitted and loss powers of the considered structure on various parameters have been investigated to observe the effect of the dissipation factor. As can be seen from the numerical results, if the dissipation factor changes, the behaviors of the powers will be affected from this change. Consequently the dissipation factor has an important role in the variations of the powers. The law of conservation of energy given by [11,14,15] is satisfied by our results. The discussed problem is useful for applications which require controlling of reflected and transmitted powers like antenna radome, microwave, millimeter wave and optical devices.

References